

Contents

Introduction	7
Chapter 1. On Process Modeling	13
1.1. Introduction	13
1.2. Model classification	14
1.2.1. Heat and mass balances	18
1.2.2. Mechanical systems	39
1.2.3. Electrical systems	50
1.3. Linearization	58
Chapter 2. Laplace Transforms and Block Diagrams	67
2.1. The Laplace transform	67
2.2. Transfer functions	69
2.3. Laplace transform calculations	72
2.4. Differential and integral equations	87
2.5. Block diagrams	99
2.6. Feedback systems	111
Chapter 3. Analysis	139
3.1. Introduction	139
3.2. Step responses	140
3.3. System identification	148
3.4. Frequency response	163
Chapter 4. Stability and the Root Locus	205
4.1. Stability	205
4.1.1. The Routh–Hurwitz criterion	207
4.1.2. Revers’s criterion	208

6 Control of Continuous Linear Systems	
4.2. The root locus	231
Chapter 5. Regulation and PID Regulators	255
5.1. Introduction	255
5.2. Direct design	259
5.3. PID tuning	269
Appendices	304
A. On Theoretical Aspects	305
A.1. The Dirac impulse	305
A.1.1. Residence time	310
A.2. The unit step	311
A.3. The Routh–Hurwitz criterion	313
A.4. The Nyquist criterion	320
A.5. The root locus	325
A.6. Computation of integrals of the form J_2	335
A.7. On non-linear systems	336
Bibliography	345
Index	349